

## Lecture 2 of 41

## Viewing 1 of 4: Overview, Projections

William H. Hsu

Department of Computing and Information Sciences, KSU

KSOL course pages: http://bit.ly/hGvXIH / http://bit.ly/eVizrE
Public mirror web site: http://www.kddresearch.org/Courses/CIS636
Instructor home page: http://www.cis.ksu.edu/~bhsu

## Readings:

Today: Sections 2.2.3 – 2.2.4, 2.8, Eberly 2° – see http://bit.ly/ieUq45

Next class: Section 2.3 (esp. 2.3.4), FVFH slides

Appendices 1-4, Foley, J. D., VanDam, A., Feiner, S. K., & Hughes, J. F. (1991).

Computer Graphics, Principles and Practice, Second Edition in C.

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## Lecture Outline

- Reading for Last Class: Sections 2.1, 2.2.1 2.2.2, Eberly 2e
- Reading for Today: Sections 2.2.3 2.2.4, 2.8 Eberly 2 °
- Reading for Next Class: Section 2.3 (esp. 2.3.4), Foley et al. Slides
- Last Time: Math Foundations, Matrix Transformations
  - \* Precalculus review: parametric equations of lines
  - \* Vector spaces and affine spaces
  - \* Linear systems, linear independence, bases, orthonormality
  - \* Cumulative Transformation Matrices (CTMs)
    - ⇒ Translation
    - ⇒ Rotation
    - ⇒ Scaling
- Today: Basic Viewing Principles
  - \* Projections: definitions, history
  - \* Perspective: optical principles, terminology
- Next Class: Viewing and Normalizing Transformations (VT/NT)

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