

# **Lecture Outline**

CIS 830: Advanced Topics in Artificial Intelligence

•	References: Chapters 2-3, Mitchell	
•	Suggested Exercises: 2.2, 2.3, 2.4, 2.6	
•	Review: Learning from Examples	
	<ul> <li>(Supervised) concept learning framework</li> </ul>	
	<ul> <li>Basic inductive learning algorithms</li> </ul>	
•	General-to-Specific Ordering over Hypotheses	
	<ul> <li>Version space: partially-ordered set (poset) formalism</li> </ul>	
	<ul> <li>Candidate elimination algorithm</li> </ul>	
	- Inductive learning	
•	Decision Trees	
	<ul> <li>Quick tutorial / review: Lectures 4-5, CIS 798, Fall 1999</li> </ul>	
	<ul> <li>See: <u>http://ringil.cis.ksu.edu/Courses/Fall-1999/CIS798/Lectures</u></li> </ul>	
•	Relation to Analytical Learning	
•	Next Class: Introduction to Artificial Neural Networks	VOII

151



		A Lea	arning	Proble	m		
	x <sub>1</sub> x <sub>2</sub> x <sub>3</sub> x <sub>4</sub>	→ → Unk → Fun	nown _ ction	,	► y = f (x <sub>1</sub>	, x <sub>2</sub> , x <sub>3</sub> , x <sub>4</sub> )	
	Example	<b>X</b> 1	<b>X</b> <sub>2</sub>	<b>X</b> 3	$x_4$	у	
	0	0	1	1	0	0	
	1	0	0	0	0	0	
	2	0	0	1	1	1	
	3	1	0	0	1	1	
	4	0	1	1	0	0	
	5	1	1	0	0	0	
	6	0	1	0	1	0	
<ul> <li>x<sub>i</sub>: t<sub>i</sub>, y:</li> <li>Our lea</li> </ul>	t, f: $(t_1 \times t_2 \times t_3)$ rning functio	$_{3} \times t_{4}) \rightarrow t$ n: Vector	$(t_1 \times t_2 \times t_3)$	$x \times t_4 \times t$ ) $\rightarrow$	$(\mathbf{t}_1 \times \mathbf{t}_2 \times \mathbf{t}_3)$	$_3 \times t_4) \rightarrow t$	KSII
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<ul> <li>  A → B   =  </li> <li> H<sup>4</sup> → H   =</li> <li>Complete  </li> <li>Need to</li> <li>After 7 e</li> </ul>	$ B  ^{ A }$   {0,1} × {0,1} gnorance: Is see every post examples, still	× {0,1}> Learnin sible inp have 2 <sup>9</sup> =	< {0,1} - Ig Poss ut/outpu = 512 pos	→ {0,1}   ible? t pair ssibilitie:	= 2 <sup>24</sup> =	65536 f	unction values
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	6	0	1	1	0	0	
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	8	1	0	0	0	?	
	9	1	0	0	1	1	
	10	1	0	1	0	?	
	11	1	0	1	1	?	
	12	1	1	0	0	0	
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				a tha Ca	noral Co	ncont	
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Supervise Example 0 1 2	ed Learni Sky Sunny Sunny Rainy	Air Temp Warm Warm Cold	Humidity Normal High High	Wind Strong Strong Strong	Water Warm Warm Warm	Forecast Same Same Change	Enjoy Sport Yes Yes No



## **Prototypical Concept Learning Tasks** Given Instances X: possible days, each described by attributes *Sky*, *AirTemp*, *Humidity*, *Wind*, *Water*, *Forecast* $\begin{array}{l} \mbox{Target function $c$ = EnjoySport: $X$ \to $H$ = {{Rainy, Sunny} $\times$ {Warm, Cold} $\times$ {Normal, High} $\times$ {None, Mild, Strong} $\times$ {Cool, Warm} $\times$ {Same, Change} $ \to $ {0, $the conduct of the second sec$ 13 Hypotheses H: conjunctions of literals (e.g., <?, Cold, High, ?, ?, ?>) Training examples D: positive and negative examples of the target function $\langle \boldsymbol{x}_{1,\boldsymbol{c}}(\boldsymbol{x}_{1})\rangle,\ldots,\langle \boldsymbol{x}_{m,\boldsymbol{c}}(\boldsymbol{x}_{m})\rangle$ Determine Hypothesis $h \in H$ such that h(x) = c(x) for all $x \in D$ Such h are consistent with the training data What Is A Concept Learning Algorithm? L: Vector ( $X \times H \equiv \text{boolean}$ ) $\rightarrow$ ( $X \rightarrow H$ ) Type of L means: given vector of examples (data set), return hypothesis h 15 h: $X \rightarrow H$ CIS 830: Advanced Topics in Artificial Intelligence









### **Representing Version Spaces**

#### Hypothesis Space

- A finite meet semilattice (partial ordering Less-Specific-Than;  $\perp \equiv all$  ?)
- Every pair of hypotheses has a greatest lower bound (GLB)  $VS_{H,D}$  = the consistent poset (partially-ordered subset of *H*)
- Definition: General Boundary
- General boundary G of version space VS<sub>H n</sub>: set of most general members
- Most general = minimal elements of  $VS_{H,D}$  = "set of necessary conditions"
- Definition: Specific Boundary
- Specific boundary S of version space  $VS_{H,D}$ : set of most specific members
- Most specific = maximal elements of  $VS_{H,D}$  = "set of sufficient conditions" Version Space
- Every member of the version space lies between *S* and *G*
- −  $VS_{H,D} \equiv \{ h \in H \mid \exists s \in S : \exists g \in G : g \leq_P h \leq_P s \}$  where  $\leq_P \equiv$  Less-Specific-Than

151

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### Terminology

### Supervised Learning

- Concept function: observations to categories; so far, boolean-valued (+/-)
- Target (function) true function f
- Hypothesis proposed function h believed to be similar to f \_
- Hypothesis space space of all hypotheses that can be generated by the earning system
- **Example** tuples of the form  $\langle x, f(x) \rangle$
- Instance space (aka example space) space of all possible examples
- Classifier discrete-valued function whose range is a set of class labels Inductive Learning
- Inductive generalization process of generating hypotheses  $h \in H$  that describe cases not yet observed
- The inductive learning hypothesis basis for inductive generalization Analytical Learning
- - Domain theory T- set of assertions to explain examples Analytical generalization - process of generating h consistent with D and T
  - 5 Explanation – proof in terms of T that x satisfies c(x)

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Summary Points						
Concept Learning as Search through H						
<ul> <li>Hypothesis space H as a state space</li> </ul>						
<ul> <li>Learning: finding the correct hypothesis</li> </ul>						
nductive Leaps Possible Only if Learner Is Biased						
- Futility of learning without bias						
<ul> <li>Strength of inductive bias: proportional to restrictions on hypotheses</li> </ul>						
Modeling Inductive Learners						
- Equivalent inductive learning, deductive inference (theorem proving) problems						
<ul> <li>Hypothesis language: syntactic restrictions (aka representation bias)</li> </ul>						
Views of Learning and Strategies						
<ul> <li>Removing uncertainty ("data compression")</li> </ul>						
- Role of knowledge						
Integrated Inductive and Analytical Learning						
- Using inductive learning to acquire domain theories for analytical learning						
<ul> <li>Roles of integrated learning in KDD</li> </ul>						
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