

## Lecture 11 of 41

# Surface Detail 2 of 5: Textures OpenGL Shading

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KSOL course pages: <http://bit.ly/hGvXIH> / <http://bit.ly/eVizrE>

Public mirror web site: <http://www.kddresearch.org/Courses/CIS636>

Instructor home page: <http://www.cis.ksu.edu/~bhsu>

### Readings:

Today: Sections 2.6.3, 20.3 – 20.4, Eberly 2<sup>e</sup> – see <http://bit.ly/ieUq45>

Next class: Sections 20.5 – 20.13, Eberly 2<sup>e</sup>

Brown CS123 slides on Polygons/Texture Mapping – <http://bit.ly/h2VZn8>

Wayback Machine archive of Brown CS123 slides: <http://bit.ly/gAhJbh>

CMU 15-462 slides on OpenGL Shading – <http://bit.ly/g1J2nj>

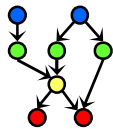




## Lecture Outline

- Reading for Last Class: §2.7, Eberly 2<sup>e</sup>; Direct 3D Handout
- Reading for Today: §2.6.3, 20.3 – 20.4, Eberly 2<sup>e</sup>
- References: Gröller & Jeschke (2002), Isenberg (2005), Jacobs (2007)
- Reading for Next Class: §20.5 – 20.13, Eberly 2<sup>e</sup>
- Last Time: Intro to Illumination and Shading
  - \* Local vs. global models
  - \* Illumination (vertex shaders) vs. shading (fragment/pixel shaders)
  - \* Bidirectional reflectance distribution function (BRDF)  $\rho(p, \omega_i, \omega_o, \lambda)$
  - \* Phong illumination equation: introduction to shading
- Texture Mapping Explained
  - \* Definitions
  - \* Design principles
- Texture Pipeline
- Using Simple Intermediate Surfaces (Cylinder, Sphere, Plane, Box)
- OpenGL Shading: Flat Shading, Smooth Shading (Gouraud)





## Where We Are

Lecture	Topic	Primary Source(s)
0	Course Overview	Chapter 1, Eberly 2 <sup>e</sup>
1	<b>CG Basics: Transformation Matrices; Lab 0</b>	<b>Sections (§) 2.1, 2.2</b>
2	Viewing 1: Overview, Projections	§ 2.2.3 – 2.2.4, 2.8
3	Viewing 2: Viewing Transformation	§ 2.3 esp. 2.3.4; <a href="#">FVFH slides</a>
4	<b>Lab 1a: Flash &amp; OpenGL Basics</b>	<b>Ch. 2, 16<sup>1</sup>, <a href="#">Angel Primer</a></b>
5	Viewing 3: Graphics Pipeline	§ 2.3 esp. 2.3.7; 2.6, 2.7
6	Scan Conversion 1: Lines, Midpoint Algorithm	§ 2.5.1, 3.1; <a href="#">FVFH slides</a>
7	<b>Viewing 4: Clipping &amp; Culling; Lab 1b</b>	<b>§ 2.3.5, 2.4, 3.1.3</b>
8	Scan Conversion 2: Polygons, Clipping Intro	§ 2.4, 2.5 esp. 2.5.4, 3.1.6
9	Surface Detail 1: Illumination & Shading	§ 2.5, 2.6.1 – 2.6.2, 4.3.2, 20.2
10	<b>Lab 2a: Direct3D / DirectX Intro</b>	<b>§ 2.7, <a href="#">Direct3D handout</a></b>
11	<b>Surface Detail 2: Textures; OpenGL Shading</b>	<b>§ 2.6.3, 20.3 – 20.4, <a href="#">Primer</a></b>
12	Surface Detail 3: Mappings; OpenGL Textures	§ 20.5 – 20.13
13	<b>Surface Detail 4: Pixel/Vertex Shad.; Lab 2b</b>	<b>§ 3.1</b>
14	Surface Detail 5: Direct3D Shading; OGLSL	§ 3.2 – 3.4, <a href="#">Direct3D handout</a>
15	Demos 1: CGA, Fun; Scene Graphs: State	§ 4.1 – 4.3, <a href="#">CGA handout</a>
16	<b>Lab 3a: Shading &amp; Transparency</b>	<b>§ 2.6, 20.1, <a href="#">Primer</a></b>
17	<b>Animation 1: Basics, Keyframes; HW/Exam</b>	<b>§ 5.1 – 5.2</b>
	<b>Exam 1 review; Hour Exam 1 (evening)</b>	<b>Chapters 1 – 4, 20</b>
18	<b>Scene Graphs: Rendering; Lab 3b: Shader</b>	<b>§ 4.4 – 4.7</b>
19	<b>Demos 2: SFX; Skinning, Morphing</b>	<b>§ 5.3 – 5.5, <a href="#">CGA handout</a></b>
20	Demos 3: Surfaces; B-reps/Volume Graphics	§ 10.4, 12.7, <a href="#">Mesh handout</a>

Lightly-shaded entries denote the due date of a written problem set; heavily-shaded entries, that of a machine problem (programming assignment); blue-shaded entries, that of a paper review; and the green-shaded entry, that of the term project.

Green, blue and red letters denote exam review, exam, and exam solution review dates.



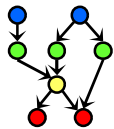


## Review: Illumination & Shading

- ▶ **Lighting**, or **illumination**, is the process of computing the intensity and color of a sample point in a scene as seen by a viewer
  - ▶ lighting is a function of the geometry of the scene (including the model, lights and camera and their spatial relationships) and material properties
- ▶ **Shading** is the process of *interpolation* of color at points in-between those with known lighting or illumination, typically vertices of triangles or quads in a mesh
  - ▶ used in many real time graphics applications (e.g., games) since calculating illumination at a point is usually expensive
- ▶ On the GPU, lighting is calculated by a **vertex shader**, while shading is done by a fragment or **pixel shader**

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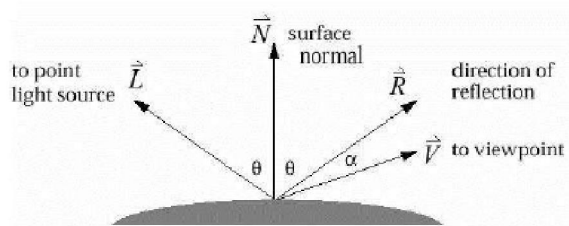


## Review: Phong Illumination Equation

- ▶ The full Phong model is a combination of the Lambertian and specular terms (summing over all the lights)

$$I_\lambda = i_{a_\lambda} k_{a_\lambda} O_{d_\lambda} + \sum_{m \in \text{lights}} f_{att} i_{d_\lambda} [k_{d_\lambda} (\mathbf{n} \cdot \mathbf{L}_m) O_{d_\lambda} + k_{s_\lambda} (\mathbf{R}_m \cdot \mathbf{V})^\alpha O_{s_\lambda}]$$

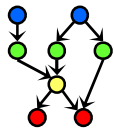
- ▶ Subscript  $s$  represents specular (so  $k_s$ ) would be the specular coefficient
- ▶  $\mathbf{R}_m$  is the reflected direction of the light ray about the surface normal
- ▶  $f_{att}$  is the lighting attenuation function
  - ▶ function of distance from the light



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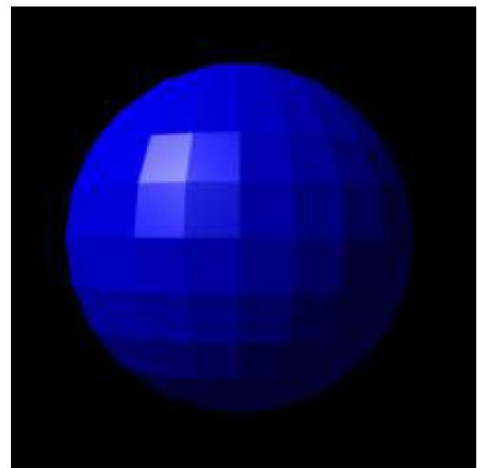
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## Review: Flat/Constant Shading

- ▶ We define a normal at each polygon (not at each vertex)
- ▶ **Lighting:** Evaluate the lighting equation at the center of each polygon using the associated normal
- ▶ **Shading:** Each sample point on the polygon is given the calculated lighting value



GL\_CONSTANT

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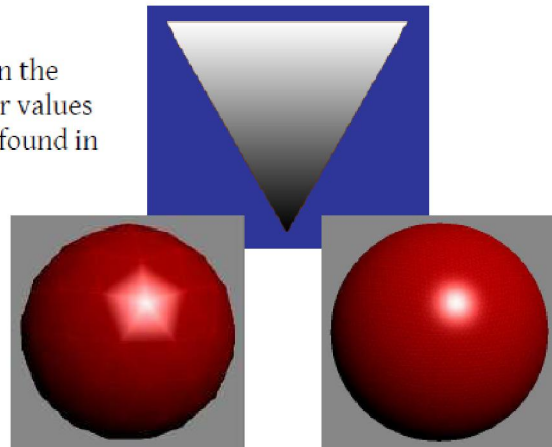




## Review: Gouraud Shading

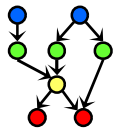
- ▶ We define a normal vector at each *vertex*
- ▶ **Lighting:** Evaluate the lighting equation at each vertex using the associated normal vector
- ▶ **Shading:** Each sample point's color on the polygon is interpolated from the color values at the polygon's vertices which were found in the lighting step

`GL_SMOOTH`



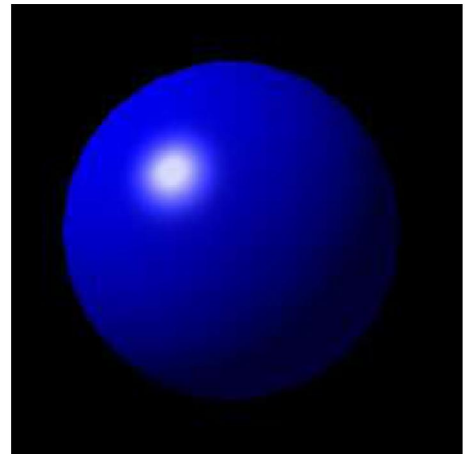
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## Review: Phong Shading

- ▶ Each vertex has an associated normal vector
- ▶ **Lighting:** Evaluate the lighting equation at each vertex using the associated normal vector
- ▶ **Shading:** For every sample point on the polygon we interpolate the normals at vertices of the polygon and compute the color using the lighting equation with the interpolated normal at each interior pixel



OpenGL implementation?  
Stay tuned...

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## Source Material on Texturing: Gröller & Jeschke (Vienna Tech)

### Texturing

Eduard Gröller  
(today: Stefan Jeschke)

Institute of Computer Graphics and Algorithms  
Vienna University of Technology



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## Other Source Material on Texture Mapping

### David W. Jacobs



Associate Professor, [Computer Science Department](#) and [UMIACS](#),  
at [the University of Maryland](#).

**CMSC 427 Computer Graphics**  
**University of Maryland – College Park (UMD)**  
**Fall 2007**  
**Course:** <http://bit.ly/fXVA1A>  
**Instructor:** <http://www.cs.umd.edu/~djacobs>



### Tobias Isenberg

**Scientific Visualization and  
Computer Graphics Group  
Department of Mathematics and  
Computing Science  
University of Groningen**

**Formerly  
Graphics Jungle Lab  
Department of Computer Science  
University of Calgary**

**CPSC 599.64/601.64 Computer Graphics**  
**Fall 2005**  
**Course:** <http://bit.ly/idD2qX>  
**Instructor:** <http://www.cs.rug.nl/~isenberg>

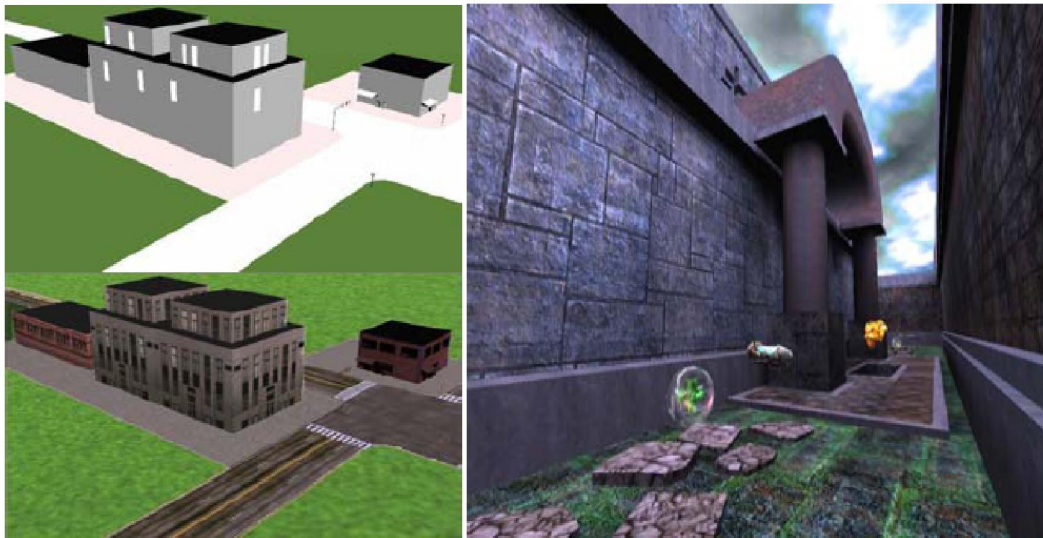
- Computer Graphics II lecture by Stefan Schlechtweg, Department of Simulation and Graphics, Otto-von-Guericke University of Magdeburg, Germany
- CPSC 407 and CPSC 453 lectures by Brian Wyvill, Department of Computer Science, University of Calgary, Canada





## Why Texturing?

- Idea: enhance visual appearance of plain surfaces by applying fine structured details



Eduard Gröller, Stefan Jeschke

1

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## Introduction [1]: Motivation

- so far: detail through polygons & materials
- example: brick wall
- problem: many polygons & materials needed for detailed structures  
→ inefficient for memory and processing
- new approach necessary: texture mapping
- introduced by Ed Catmull (1974),  
extended by Jim Blinn (1976)



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## Introduction [2]: Properties and their Mappings

- several properties can be modified
  - color: diffuse component of surface
  - reflection: specular component of surface to simulate reflection (environment mapping)
  - normal vector: simulate 3D surface structure (bump mapping)
  - actual surface: raise/lower points to actually modify surface (displacement mapping)
  - transparency: make parts of a surface entirely or to a certain degree transparent

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## Concerning Textures

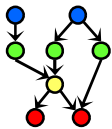
- Pattern of Intensity and color.
  - Can be generalized to 3D texture.
- How do we get them?
  - Take pictures.
  - Write a program (procedural textures).
  - Synthesize from examples
- How do we apply them? (Texture mapping)
  - Specify a mapping from texture to object.
  - Interpolate as needed.
  - This can be a challenging problem, but we'll consider simpler version.

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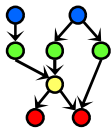
## Without Textures



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## With Textures

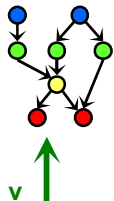


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## Texture Image



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## Acknowledgements



**Andy van Dam**  
T. J. Watson University Professor of  
Technology and Education &  
Professor of Computer Science  
Brown University  
<http://www.cs.brown.edu/~avd/>



Texture Mapping

Beautification of Surfaces

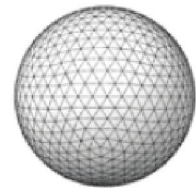
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## Texture Mapping Overview [1]: Technique

- ▶ Texture mapping:
  - ▶ Implemented in hardware on every gpu
  - ▶ Simplest surface detail hack, dating back to the '60s GE flight simulator and its terrain generator
- ▶ Technique:
  - ▶ "Paste" photograph or bitmap (the texture, for example: a brick pattern, a wood grain pattern, a sky with clouds) on a surface to add detail without adding more polygons.
  - ▶ Map texture onto the surface get the surface color or alter the object's surface color
  - ▶ Think of texture map as stretchable contact paper



Sphere with no texture



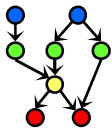
Texture image



Sphere with texture

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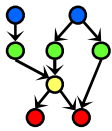


## Texture Mapping Overview [2]: Motivation

- ▶ How do we add more detail to a model?
  - ▶ Add more detailed geometry; more, smaller triangles:
    - ▶ Pros: Responds realistically to lighting, other surface interaction
    - ▶ Cons: Difficult to generate, takes longer to render, takes more memory space
  - ▶ Map a texture to a model:
    - ▶ Pros: Can be stored once and reused, easily compressed to reduce size, rendered very quickly, very intuitive to use, especially useful on far-away objects, terrain, sky,...
    - ▶ Cons: Very crude approximation of real life. Texture mapped but otherwise unaltered surfaces still look smooth.
- ▶ What can you put in a texture map?
  - ▶ Diffuse, ambient, specular, or any kind of color
  - ▶ Specular exponents, transparency or reflectivity coefficients
  - ▶ Surface normal data (for bump mapping or normal mapping)
  - ▶ Projected reflections or shadows

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## Texture Mapping Overview [3]: Mappings

- ▶ A function is a mapping
  - ▶ Takes any value in the domain as an input and outputs ("maps it to") one unique value in the co-domain.
- ▶ Mappings in "Intersect": linear transformations with matrices
  - ▶ Map screen space points (input) to camera space rays (output)
  - ▶ Map camera space rays into world space rays
  - ▶ Map world space rays into un-transformed object space for intersecting
  - ▶ Map intersection point normals to world space for lighting
- ▶ Mapping a texture:
  - ▶ Take points on the surface of an object (domain)
  - ▶ Return an entry in the texture (co-domain)

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## Texture Mapping How-To [1]: Goals and Texture Elements (Texels)

- **texture**: typically 2D pixel image
- **texel**: pixel in a texture
- determines the appearance of a surface
- procedure to map the texture onto the surface needed
  - easy for single triangle
  - complex for arbitrary 3D surface
- goal: find easy way to do this mapping

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## Texture Mapping How-To [2]: Adapting Polygons-to-Pixels Pipeline

- rendering pipeline slightly modified to use new texture mapping function
- algorithm: for each pixel to be rendered
  - find depicted surface point
  - find point in texture (texel) that corresponds to surface point
  - use texel color to modify the pixel's shading

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## Texture Mapping How-To [3]: Mapping Definition

- 2D texture: function that maps points on the  $(u, v)$  plane to  $(r, g, b)$  values:  
 $(r, g, b) = c_{\text{tex}}(u, v)$
- texture mapping function maps  $(u, v)$  values to  $(x, y, z)$  positions on objects:  
 $(x, y, z) = F_{\text{map}}(u, v)$
- we need to solve the inverse function to find  $(u, v)$  values for a  $(x, y, z)$  position:  
 $(u, v) = F_{\text{map}}^{-1}(x, y, z)$ 

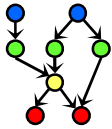
$u = s(x, y, z)$   
 $v = t(x, y, z)$

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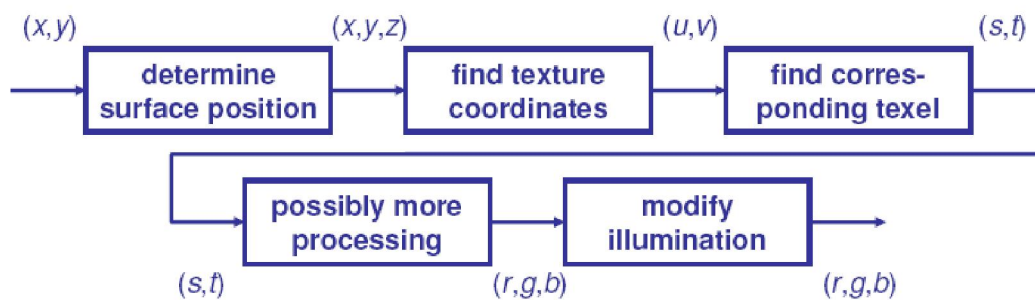






## Texture Mapping How-To [4]: General Procedure

- general texture mapping pipeline:



1. compute texture color for surface point
2. use to modify parameters in Phong illumination

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## Texture Mapping How-To [5]: Projective Textures, Functions

- goal: derive texture coordinates from 3D point
- $P: \mathbb{R}^3 \rightarrow \mathbb{R}^2$ , so  $P(x, y, z) = (u, v)$
- several typical possibilities
  - (manual) parameterization of the surface
  - use of inherent  $(u, v)$  coordinates (e.g., freeform surfaces or primitive shapes)
  - two step technique

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## Texture Mapping How-To [6]: (Manual) Surface Parameterization

- simplest technique
- specification of texture coordinates during modeling
- $(u, v)$  coordinates specified for all vertices of a polygon
- interpolation between these values for points inside the polygon (e.g. barycentric interpolation for triangles)

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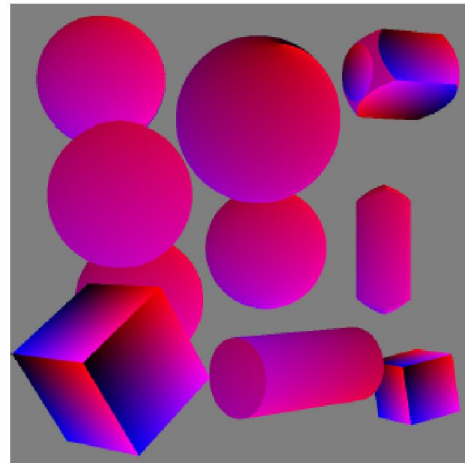
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## Texture Mapping How-To [7]: Inherent $(u, v)$ Coordinates

- $(u, v)$  coordinates derived from parameter directions of surface patches (e.g., Bézier and spline patches)
- obvious  $(u, v)$  coordinates derived for primitive shapes (e.g., boxes, spheres, cones, cylinders, etc.)
- used as defaults



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## Two-Step Approach [1]: Duality (Again)

- two steps:
  - mapping of 2D texture coordinates onto simple 3D surface (s-mapping)
  - mapping of the now 3D texture pattern onto complex object (o-mapping)
- in practice – inverse approach:
  - mapping of object point onto simple surface  
 $O: f(x_o, y_o, z_o) = (x_i, y_i, z_i)$
  - mapping of surface point onto texture  
 $S: f(x_i, y_i, z_i) = (u, v)$





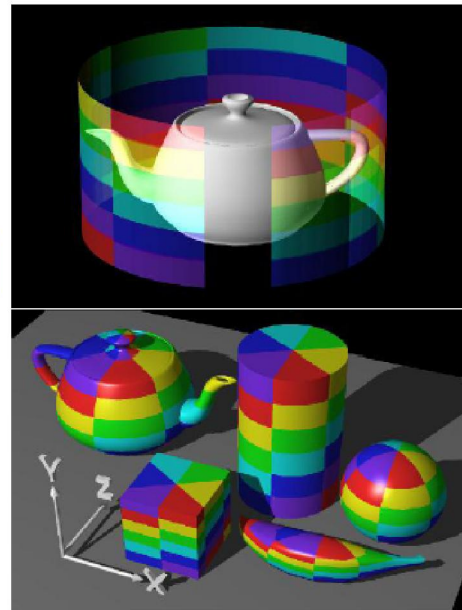
## Two-Step Approach [2]: Example – Cylindrical Mapping

- mapping onto cylinder surface given by height  $h_0$  and angle  $\theta_0$

$$S : (\theta, h) \rightarrow (u, v) = \left( \frac{r}{c}(\theta - \theta_0), \frac{1}{d}(h - h_0) \right)$$

using scaling factors  $c$ ,  $d$ , and the radius  $r$

- discontinuity along one line parallel to center axis



from R. Wolfe: *Teaching Texture Mapping*

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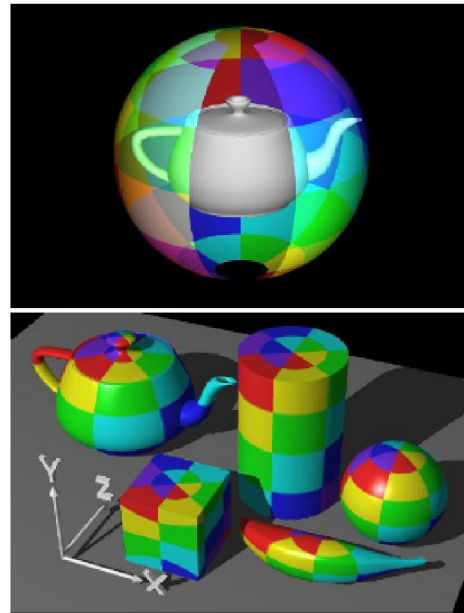


## Two-Step Approach [3]: Example – Spherical Mapping

- mapping onto surface of a sphere given by spherical coordinates

$$S : (r, \phi, \theta) \rightarrow (u, v) = \left( \frac{\theta}{2\pi}, \frac{(\pi/2) + \phi}{\pi} \right)$$

- no non-distorting mapping possible between plane and sphere surface



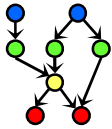
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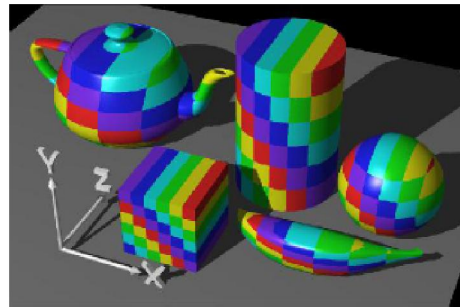
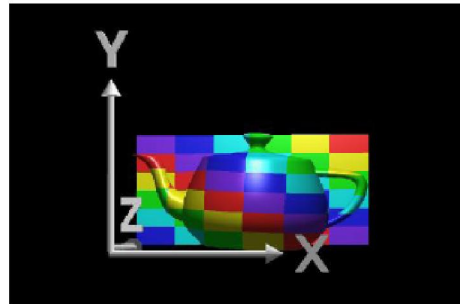


## Two-Step Approach [4]: Example – Planar Mapping

- mapping onto planar surface given by position vector  $\vec{v}_0$  and two vectors  $\vec{s}$  and  $\vec{t}$

$$S : (x, y, z) \rightarrow (u, v) = \left( \frac{\vec{v} \cdot \vec{s}}{k}, \frac{\vec{v} \cdot \vec{t}}{k} \right)$$

- scaling factor  $k$  and  $\vec{V} = \vec{P}_i - \vec{v}_0$  (describes point position w.r.t. the origin of the plane)



from R. Wolfe: *Teaching Texture Mapping*

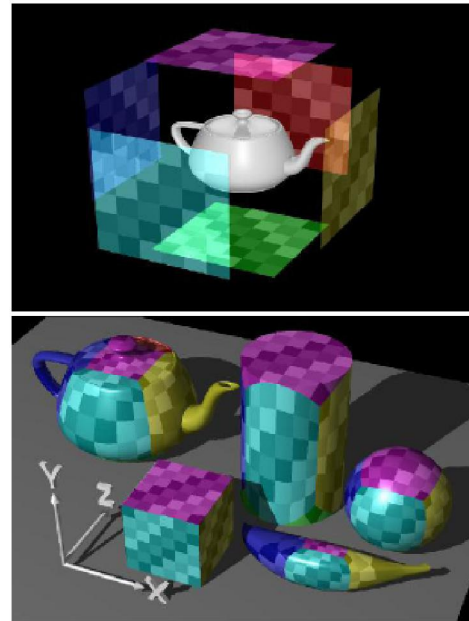






## Two-Step Approach [5]: Example – Cuboid/Box Mapping

- enclosing box is usually axis-parallel bounding box of object
- six rectangles onto which the texture is mapped
- similar to planar mapping



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## *O Mapping [1]: Object-to-Surface*

- necessary for all named techniques
- four methods
  - *reflected ray*: trace a ray from viewer to object and reflect it onto the intermediate surface
  - *object normal*: intersection of normal vector of object with intermediate surface
  - *object center*: intersection of ray from object center through the object surface with the intermediate surface
  - *normal of intermediate surface*: trace this normal vector towards the object and determine intersection with it

Adapted from slides

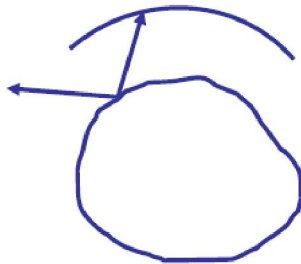
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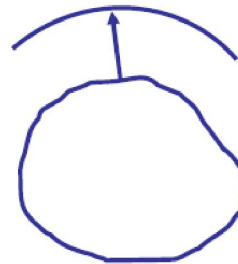


## O Mapping [2]: Illustrations

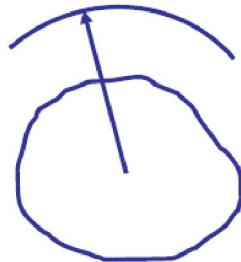
1. Reflected Ray



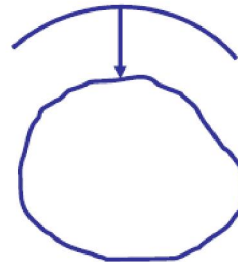
2. Object Normal



3. Object Center



4. Normal of Intermediate Surface



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## Correspondence Functions [1]: Texture Coordinates

- projector functions yield  $(u, v)$  coordinates in texture parameter space
- typically values of  $u$  and  $v$  in  $[0, 1]$
- correspondence functions transform these into texel positions
- rotations, translations, scaling possible
- in most simple cases only scaling necessary

$$u = s(x, y, z)$$
$$v = t(x, y, z)$$

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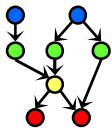
## Correspondence Functions [2]: Tiling, Mirroring, Clamping, Borders

- problem: what happens outside of  $[0, 1]$ ?
- typical approaches
  - texture repetition (tiling) using modulo function
  - texture mirroring – better continuity at texture seams
  - clamping: repeat the last value of the texture edges for values outside of  $[0, 1]$
  - border color: use a specified color for all non-defined values

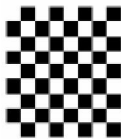
Adapted from slides

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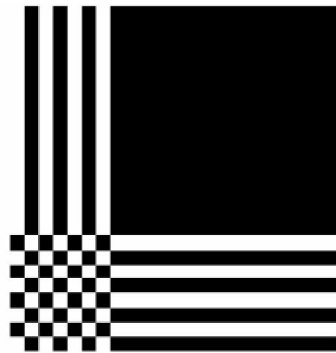




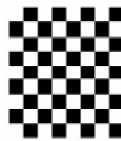
## Correspondence Functions [3]: Clamping and Borders Illustrated



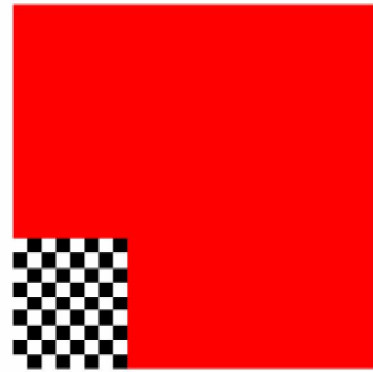
Texture



Clamped texture applied to primitive



Texture



Texture with red border applied to primitive

from Microsoft Developer Network

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## Application of Texture Values: Combining Texturing and Lighting

- from an  $(x, y, z)$  position we derived an  $(r, g, b)$  color value from the texture, potentially with  $\alpha$  transparency value
- is typically used to modify illumination
- methods:
  - replace: surface color value is replaced with texture color
  - decal:  $\alpha$  blending of texture and original color
  - modulate: multiplication of original color value with texture color

Adapted from slides

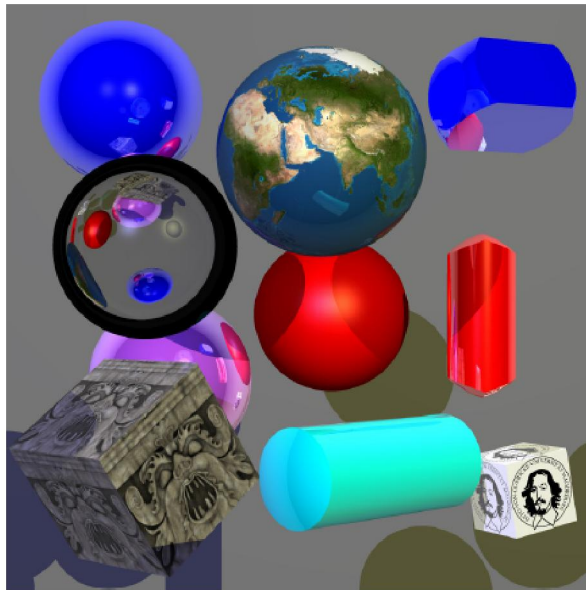
© 2005 Isenberg, T., University of Calgary (now at U. Groningen)





## The End...?

Done! ... well, almost

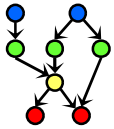


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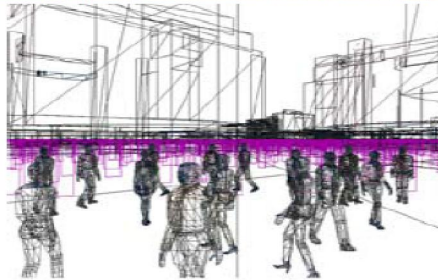
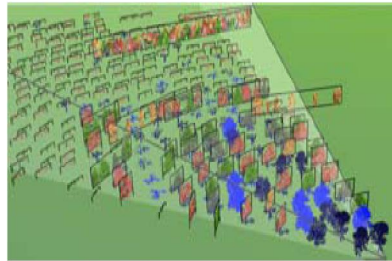
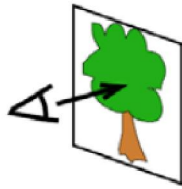






## Surface Detail: Imitating Complexity by Texturing Smooth Objects

- Also possible: model very complex objects just by using simple textured geometry



Adapted from slides

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## More on Shading (Surface Detail 2, 4, 5)

- **Shading in OpenGL**
  - \* Flat/constant: `GL_CONSTANT`
  - \* Gouraud: `GL_SMOOTH`
- **Shading Languages**
  - \* Renderman Shading Language (RSL) – <http://bit.ly/g229q4>
  - \* OpenGL Shading Language (OGLSL or GLSL) – <http://bit.ly/fX8V0Y>
  - \* Microsoft High-Level Shading Language (HLSL) – <http://bit.ly/eVnjp5>
  - \* nVidia Cg – <http://bit.ly/ewoRic>
- **Vertex vs. Pixel Shaders**
- **How to Write Shaders**



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## Source Material on OpenGL Shading

15-462 Computer Graphics I  
Lecture 8

### Shading in OpenGL

Polygonal Shading  
Light Source in OpenGL  
Material Properties in OpenGL  
Normal Vectors in OpenGL  
Approximating a Sphere  
[Angel 6.5-6.9]

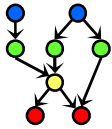
February 14, 2002  
Frank Pfenning  
Carnegie Mellon University

<http://www.cs.cmu.edu/~fp/courses/graphics/>

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<http://bit.ly/g1J2nj>

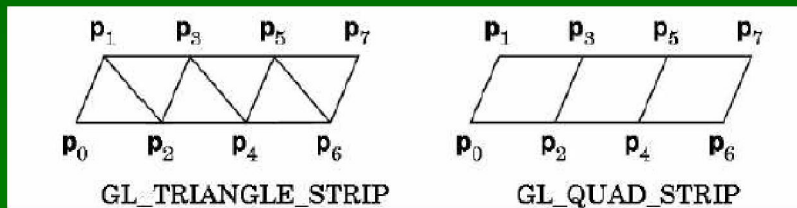




## Shading in OpenGL [1]: Flat Shading

- Normal: given explicitly before vertex  

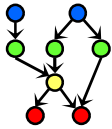
```
glNormal3f(nx, ny, nz);
glVertex3f(x, y, z);
```
- Shading constant across polygon
- Single polygon: first vertex
- Triangle strip: Vertex  $n+2$  for triangle  $n$



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<http://bit.ly/g1J2nj>





## Shading in OpenGL [2]: Interpolative (aka Smooth), Gouraud

### ● Interpolative Shading

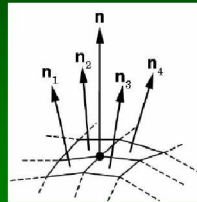
- Enable with `glShadeModel(GL_SMOOTH);`
- Calculate color at each vertex
- Interpolate color in interior
- Compute during scan conversion (rasterization)
- Much better image (see Assignment 1)
- More expensive to calculate

### ● Gouraud Shading

- Special case of interpolative shading
- How do we calculate vertex normals?
- Gouraud: average all adjacent face normals

$$\mathbf{n} = \frac{\mathbf{n}_1 + \mathbf{n}_2 + \mathbf{n}_3 + \mathbf{n}_4}{|\mathbf{n}_1 + \mathbf{n}_2 + \mathbf{n}_3 + \mathbf{n}_4|}$$

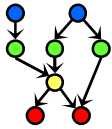
- Requires knowledge about which faces share a vertex



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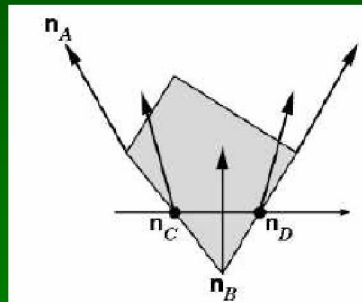
<http://bit.ly/g1J2nj>





## Shading in OpenGL [3]: Phong Shading

- Interpolate **normals** rather than colors
- Significantly more expensive
- Mostly done off-line (not supported in OpenGL)



... kind of  
-WHH

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## Shading in OpenGL [5]: Specifying & Enabling Light Sources

### ● Enabling Light Sources

- Lighting in general must be enabled  
`glEnable(GL_LIGHTING);`
- Each individual light must be enabled  
`glEnable(GL_LIGHT0);`
- OpenGL supports at least 8 light sources

### ● Specifying Point Light Source

- Use vectors  $\{r, g, b, a\}$  for light properties
- Beware: light source will be transformed!

```
GLfloat light_ambient[] = {0.2, 0.2, 0.2, 1.0};
GLfloat light_diffuse[] = {1.0, 1.0, 1.0, 1.0};
GLfloat light_specular[] = {1.0, 1.0, 1.0, 1.0};
GLfloat light_position[] = {-1.0, 1.0, -1.0, 0.0};
glLightfv(GL_LIGHT0, GL_AMBIENT, light_ambient);
glLightfv(GL_LIGHT0, GL_DIFFUSE, light_diffuse);
glLightfv(GL_LIGHT0, GL_SPECULAR, light_specular);
glLightfv(GL_LIGHT0, GL_POSITION, light_position);
```

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<http://bit.ly/g1J2nj>







## Shading in OpenGL [6]: Global Ambient Light

- Set ambient intensity for entire scene  

```
GLfloat al[] = {0.2, 0.2, 0.2, 1.0};  
glLightModelfv(GL_LIGHT_MODEL_AMBIENT, al);
```
- The above is default
- Also: local vs infinite viewer  

```
glLightModeli(GL_LIGHT_MODEL_LOCAL_VIEWER,  
              GL_TRUE);
```
- More expensive, but sometimes more accurate

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<http://bit.ly/g1J2nj>





## Shading in OpenGL [7]: Point Sources vs. Directional

- **Directional Lights versus Point Lights**

- Directional light given by “position” **vector**

```
GLfloat light_position[] = {-1.0, 1.0, -1.0, 0.0};
glLightfv(GL_LIGHT0, GL_POSITION, light_position);
```
- Point source given by “position” **point**

```
GLfloat light_position[] = {-1.0, 1.0, -1.0, 1.0};
glLightfv(GL_LIGHT0, GL_POSITION, light_position);
```

- **Spotlights: Special Case of Point Lights**

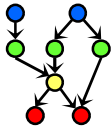
- Create point source as before
- Specify additional properties to create spotlight
 

```
GLfloat sd[] = {-1.0, -1.0, 0.0};
glLightfv(GL_LIGHT0, GL_SPOT_DIRECTION, sd);
glLightf(GL_LIGHT0, GL_SPOT_CUTOFF, 45.0);
glLightf(GL_LIGHT0, GL_SPOT_EXPONENT, 2.0);
```

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<http://bit.ly/g1J2nj>





## Shading in OpenGL [8]: Example Material Properties

```
GLfloat mat_specular[]={0.0, 0.0, 0.0, 1.0};
GLfloat mat_diffuse[]={0.8, 0.6, 0.4, 1.0};
GLfloat mat_ambient[]={0.8, 0.6, 0.4, 1.0};
GLfloat mat_shininess={20.0};
glMaterialfv(GL_FRONT, GL_SPECULAR, mat_specular);
glMaterialfv(GL_FRONT, GL_AMBIENT, mat_ambient);
glMaterialfv(GL_FRONT, GL_DIFFUSE, mat_diffuse);
glMaterialf(GL_FRONT, GL_SHININESS, mat_shininess);

glShadeModel(GL_SMOOTH); /*enable smooth shading */
glEnable(GL_LIGHTING); /* enable lighting */
glEnable(GL_LIGHT0); /* enable light 0 */
```

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<http://bit.ly/g1J2nj>





## Summary

- **Last Time: Intro to Illumination and Shading**
  - ✱ Local vs. global models
  - ✱ Illumination (vertex shaders) vs. shading (fragment/pixel shaders)
  - ✱ Phong illumination: derivation of ambient, diffuse, specular terms
  - ✱ Introduction to shading
- **Texturing: Adding Detail, Raster Image, Color, etc. to CG Model**
- **Texture Pipeline**
  - ✱ Part of polygons-to-pixels
  - ✱ Uses same spaces (coordinate systems) and more
- **Using Simple Intermediate Surfaces (Cylinder, Sphere, Plane, Box)**
- **OpenGL Shading: Flat aka Constant, Interpolative (Specifically, Gouraud)**
- **Next: Patterns, Procedural Textures, Anisotropic Filtering**
- **References: Gröller & Jeschke (2002), Isenberg (2005), Jacobs (2007)**





## Terminology

- **Texture Map / Texture Mapping**
  - \* Method of adding surface detail to CGI or 3-D model (Wikipedia)
  - \* Kinds of surface detail
    - Detail: roughness, grain, bumps/dimples, etc.
    - Surface texture: finish, veneer, etc. (represented by raster image)
    - Color: monochrome, patterns, polychromatic
- **Coordinate Systems (Spaces)**
  - \* Model / Object: 3-D (x, y, z)
  - \* World / Scene: 3-D (x, y, z)
  - \* Camera / Eye: 3-D (u, v, n)
  - \* Window / Screen: 2-D (u, v)
  - \* Texture: 1-D, 2-D, or 3-D; (s, t) for 2-D
- **Texture Pipeline – End-to-End System for Calculating, Applying Textures**
- **Gouraud Shading – Interpolative Shading with Color Interpolation**

